Investigating Mixed-Integer Hulls using a MIP-Solver

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Joint work with Volker Kaibel (OvGU)

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- Polyhedral Combinatorics
 - Introduction
 - Usual Approach
 - Limitations
- 2 Vision
- 3 Affine Hull
- 4 Facets
 - Polarity
 - 2 Algorithm
- Minimizing the 1-Norm of Basis Vectors
 - Problem
 - 2 Vectors: Exact Approach
 - 3 2 Vectors: Heuristic Approach



Problems in Question

We consider mixed-integer programs with rational data:

$$\max \langle c, x \rangle$$

s.t.

$$Ax \leq b$$

$$Cx = d$$

$$x_i \in \mathbb{Z}$$

$$\forall i \in I \subseteq [n]$$

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Denote by $R = \{x \in \mathbb{R}^n : Ax \le b, Cx = d\}$ the relaxation polyhedron and by $P = \text{conv.hull } \{x \in R : x_i \in \mathbb{Z} \ \forall i \in I\}$ the mixed-integer hull.

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Facts

- P is a polyhedron again.
- For most (e.g., NP-hard) problems, P has many facets.
- ▶ Nevertheless, MIP-solvers are really fast these days.

Another Fact

The time a MIP-solver needs for solving depends on the strength of the relaxation, i.e., how well P is approximated by R.

Polyhedral Combinatorics

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Strengthening a Relaxation

- ▶ Generic cutting planes: GMI, MIR, CG, Lift & Project, ...
- ▶ Problem-specific inequalities: Problem-dependent



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Goals of Polyhedral Combinatorics

Given a MIP-model for a problem,

- find inequalities valid for P (but not for R),
- develop algorithms (exact or heuristics) to separate these inequalities if there are too many,
- b determine the dimension of P, i.e., find valid equations,
- ▶ and prove if/when the inequalities define facets of *P*.



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Step 1: Find all feasible points

- (a) By hand / handcrafted software
- (b) Some tool, e.g. PORTA's vint functionality or azove



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There are quite a few tools (PORTA, Polymake, azove) and several algorithms:

- ► The Beneath-and-Beyond method
- ▶ The Double-Description method
- ► Lexicographic Reverse Search
- Pyramid decomposition (mixture of beneath-and-beyond and Fourier-Motzkin)

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Step 3: Generalize Inequalities

There's only one main tool here: The mathematician.

Memory and Time

The dominant of the cut polytope (corresponds to MinCut problem) has among others a facet per disjoint union of cycles joined together by any spanning tree!

ALEVRAS ('99) enumerated the facets for this polyhedron for the complete graph on 8 nodes, including 2 billions of the above type.

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Specific Objective Functions

Which are the facets useful when optimizing specific objective functions?



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Fact Reminder

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Goal of this work:

Use MIP-solvers to determine facets!



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We call a MIP-oracle stable if all reported solutions are correct after replacing the floating-point numbers by the best approximation w.r.t. to given tolerances.

Note: A rational number p/q with $p, q \in \mathbb{Z}$ is a best approximation for $x \in \mathbb{R}$ if $|x - p/q| \le |x - p'/q'|$ holds for all $p', q' \in \mathbb{Z}$ with $q' \le q$.

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Question: How does such an oracle look like in practice? Answer: SCIP* and some luck with the numerics!

Computing the Affine Hull

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Input:

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- Dimension of P
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- **1** Maintain known equations Cx = d and points $x_1, x_2, \dots, x_\ell \subseteq P$.
- Let A be matrix C with additional rows $x_i x_1$ for $i = 2, ..., \ell$.

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 - 1 Let $\{c_1, \ldots, c_t\}$ be a basis of ker A.

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 - 1 Let $\{c_1, \ldots, c_t\}$ be a basis of ker A.
 - For all $i \in [t]$ do:
 - Compute an optimal solution q_i by maximizing c_i over P. If $\langle c, q_i \rangle > \langle c, x_1 \rangle$, add $x_{\ell+1} := q_i$, add row $x_{\ell+1} - x_1$ to A, and increment ℓ .
 - Otherwise, compute an optimal solution q'_i by minimizing c_i over P. If $\langle c, q'_i \rangle < \langle c, x_1 \rangle$, add $x_{\ell+1} := q'_i$, add row $x_{\ell+1} - x_1$ to A, and increment ℓ .

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- Let A be matrix C with additional rows $x_i x_1$ for $i = 2, ..., \ell$.
- **3** While rank A < n do:
 - Let $\{c_1, \ldots, c_t\}$ be a basis of ker A.
 - **2** For all $i \in [t]$ do:
 - **1** Compute an optimal solution q_i by maximizing c_i over P.
 - If $\langle c, q_i \rangle > \langle c, x_1 \rangle$, add $x_{\ell+1} := q_i$, add row $x_{\ell+1} x_1$ to A, and increment ℓ .
 - Otherwise, compute an optimal solution q_i' by minimizing c_i over P. If $\langle c, q_i' \rangle < \langle c, x_1 \rangle$, add $x_{\ell+1} := q_i'$, add row $x_{\ell+1} x_1$ to A, and increment ℓ .
 - Otherwise, $\langle c, x \rangle = \langle c, x_1 \rangle$ defines a valid equation for P and hence can be added to Cx = d. Add row c to A

Computing the Affine Hull (cont.)

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Remark

- We can initialize Cx = g with equations from LP relaxation.
- Optimizing in unit directions is cheap but yields few points.
- Optimizing in random directions is expensive and results in more points.



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What is so special about x_1 in $x_i - x_1$ for $i = 2, ..., \ell$?

Lemma

The rank of all matrices with rows $\{x_i - x_j : \{i, j\} \in T\}$ is constant over all edge sets T which span the node set $\lfloor \ell \rfloor$.

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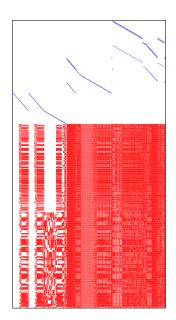
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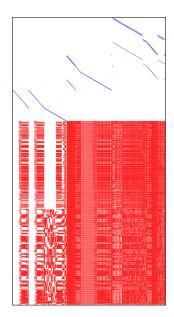
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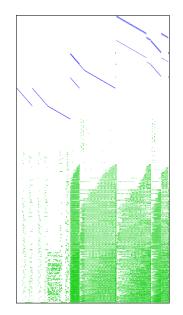
The rank of all matrices with rows $\{x_i - x_j : \{i, j\} \in T\}$ is constant over all edge sets T which span the node set $[\ell]$.

Application

Instead of the rows $x_i - x_1$ for $i = 2, ..., \ell$, we use $x_i - x_j$ for all minimum spanning tree edges $\{i, j\}$ where the weights are the number of nonzeros of $x_i - x_j$. This leads to a sparse (but equivalent) matrix A.







Definition

Let $P \subseteq \mathbb{R}^n$ be a polyhedron with \mathbb{O}_n in its relative interior. Then the set

$$\{y \in \mathbb{R}^n : \langle y, x \rangle \le 1 \ \forall x \in P\}$$

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Since the polar dual has a lineality space if P is not full-dimensional, let

$$P^* := \{ y \in \mathsf{aff.hull}(P) : \langle y, x \rangle \le 1 \ \forall x \in P \} \ .$$

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Proposition (see Schrijver '86)

- $(P^*)^* = P$
- ▶ x is a point in (vertex of) P if and only if $\langle x, y \rangle \leq 1$ defines an inequality for (facet of) P^* .
- ▶ P* is bounded if and only if P contains in its relative interior.

...once

We are given a point $\hat{x} \in R \setminus P$. Find a facet $\langle y, x \rangle \leq 1$ of P cutting off \hat{x} !

Suppose \bigcirc is in the relative interior of P.

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We are given a point $\hat{x} \in R \setminus P$. Find a facet $\langle y, x \rangle \leq 1$ of P cutting off \hat{x} ! $\langle y, x \rangle < 1$ is a facet of P and $\langle y, \hat{x} \rangle > 1$

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Hence, such a y can be found by maximizing \hat{x} over P^* .

Using Polarity . . .

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Polyhedral Comb.

Affine Hull Facets Min 1-Norm Final Slide

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- Let R be any bounded relaxation of P and define $Q:=(\Delta-o)^*\supseteq (P-o)^*.$

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 - While $\hat{y} \notin (P o)^*$ do:
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Very related work: Target Cuts by BUCHHEIM, LIERS & OSWALD, '08

1-Norm Minimization

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Motivation

- ► Readability of produced equations & facets!

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- ▶ $\langle a, x \rangle \leq \beta$ with $a \in \mathbb{Z}^n$ and $\beta \in \mathbb{Z}$ where (a^T, β) is a primitive vector.
- ▶ If $\dim(P) \neq n$, facet representations are not unique and equation normals are an arbitrary basis of aff.hull $(P)^{\perp}$.

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Problem (1-Norm Minimization in Dimension Two)

Input are two linearly independent vectors $u, v \in \mathbb{Z}^n$.

Find $\lambda, \mu \in \mathbb{Q}$ with $\lambda \neq 0$ and $\lambda u + \mu v \in \mathbb{Z}^n$ minimizing $|\lambda u + \mu v|_1$.

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Lemma

By computing the Hermite-Normal-Form of $\binom{u^T}{v^T} \in \mathbb{Z}^{2 \times n}$, we can replace u, v by a lattice basis u', v' of $\lim (u, v) \cap \mathbb{Z}^n$...

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Lemma

By computing the Hermite-Normal-Form of $\begin{pmatrix} u^T \\ v^T \end{pmatrix} \in \mathbb{Z}^{2 \times n}$, we can replace u, v by a lattice basis u', v' of $\lim (u, v) \cap \mathbb{Z}^n \dots$... such that $\lambda u' + \mu v'$ is a multiple of u if and only if $\lambda = 0$. Input are two linearly independent vectors $u, v \in \mathbb{Z}^n$.

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Problem (Restricted 1-Norm Minimization in Dimension Two)

Given a lattice basis $u, v \in \mathbb{Z}^n$, find $\lambda, \mu \in \mathbb{Z}$ with $\lambda > 0$ minimizing $|\lambda u + \mu v|_1$.

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Lemma

Let $u, v \in \mathbb{Z}^n$ be lin. independent. Let $-\infty = q_0 < q_1 < \ldots < q_{k-1} < q_k = \infty$ be the sorted elements of $Q := \left\{ -\frac{u_i}{v_i} : i \in [n], v_i \neq 0 \right\} \cup \{\pm \infty\}$.

Then the sign-pattern of $\lambda u + \mu v$ is constant over all multiplier pairs λ, μ with with $\lambda > 0$ for which λ/μ is in any fixed interval $[q_{j-1}, q_j]$.

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Final Step: In such an interval the 1-norm is linear and integer programming in dimension 2 can be solved efficiently (see EISENBRAND & LAUE, 0.03).

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Heuristic:

- Let $w := \mu$
- For all $i \in [n]$ with $v_i \neq 0$ do:
 - 1 Let $w^{(i)} := v_i \cdot \mu \mu_i \cdot v_i$
 - Divide $w^{(i)}$ by the g.c.d. of its entries.
 - **3** If $|w^{(i)}|_1 < |w|_1$, replace w by $w^{(i)}$.
- Return w.

Questions? Polyhedral Comb. Vision Affine Hull Facets Min 1-Norm Final Slide

Problems to be tackled by help of MIP-solvers:

- Compute all valid equations / the dimension d.
- Find facets useful when optimizing certain objective functions, together with d independent points proving that it is a facet.
- ▶ Compute the dimension of other faces, e.g. the optimal face.
- ► Compute the conflict graph for 0/1-variables.



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To be done:

- ► Finish basic code :-)
- Improve convergence for cutting plane procedure.
- Carry out computational study.
- Find some nice facets for interesting polytopes.

