

Indicator Constraints in Mixed-Integer Programming

Andrea Lodi

University of Bologna, Italy - `andrea.lodi@unibo.it`

Amaya Nogales-Gómez, Universidad de Sevilla, Spain

Pietro Belotti, FICO, UK

Matteo Fischetti, Michele Monaci, Domenico Salvagnin, University of Padova, Italy

Pierre Bonami, IBM, Spain

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Indicator (bigM's) constraints

- We consider the linear inequality

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where $x \in \mathbb{R}^k$ and $(a, a_0) \in \mathbb{R}^{k+1}$ are constant.

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- It is a well-known **modeling trick** in Mixed-Integer Linear Programming (MILP) to use a **binary variable** y multiplied by a **sufficiently big** (positive) constant M in order to **deactivate constraint** (1)

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$$a^T x \leq a_0 + My. \quad (2)$$

- It is also well known the **risk** of such a modeling trick, namely
 - **weak Linear Programming** (LP) relaxations, and
 - **numerical issues**.

Complementarity Reformulation

- An **alternative** for logical implications and general deactivations is given by the **complementary** reformulation

$$(a^T x - a_0)\bar{y} \leq 0, \quad (3)$$

where $\bar{y} = 1 - y$. It has been used for decades in the Mixed-Integer Nonlinear Programming literature (MINLP).

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- The obvious drawback of the above reformulation is its **nonconvexity**.
- Thus, the complementary reformulation has been used so far **if (and only if)** the problem at hand was **already nonconvex**, as it is often the case, for example, in Chemical Engineering applications.

Our goal

- In this talk we **argue against this common rule** of always pursuing a linear reformulation for logical implications.

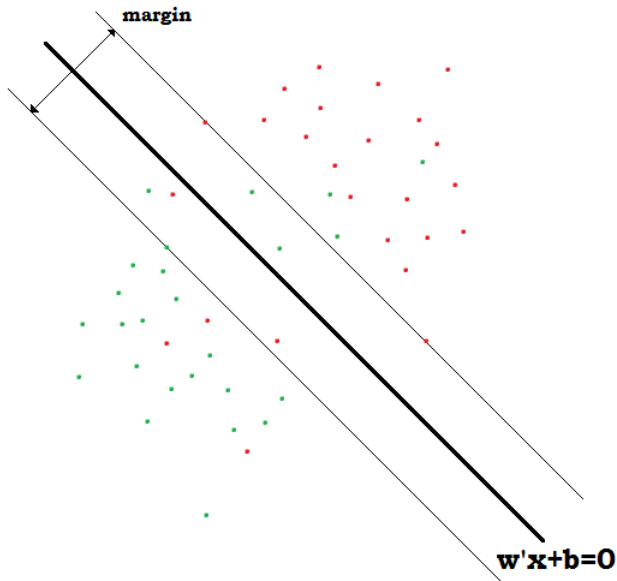
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- In this talk we **argue against this common rule** of always pursuing a linear reformulation for logical implications.
- We do that by **exposing a class** of Mixed-Integer Convex Quadratic Programming (MIQP) problems arising in *Supervised Classification* where the Global Optimization (GO) solver Couenne using reformulation (3) is **out-of-the-box consistently faster than** virtually any state-of-the-art commercial **MIQP solver** like IBM-Cplex, Gurobi and Xpress.

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- This is quite **counter-intuitive** because, in general, convex MIQPs admit more efficient solution techniques both in theory and in practice, especially because they benefit of virtually all machinery of MILP solvers.

Support Vector Machine (SVM)



The input data

- Ω : the population.
- Population is partitioned into **two classes**, $\{-1, +1\}$.
- For each object in Ω , we have
 - $x = (x^1, \dots, x^d) \in X \subset \mathbb{R}^d$: predictor variables.
 - $y \in \{-1, +1\}$: **class membership**.
- The goal is to **find a hyperplane** $\omega^\top x + b = 0$ that aims at **separating**, if possible, **the two classes**.
- Future objects will be classified as

$$\begin{aligned} y &= +1 & \text{if } \omega^\top x + b > 0 \\ y &= -1 & \text{if } \omega^\top x + b < 0 \end{aligned} \tag{4}$$

Soft-margin approach

$$\min \frac{\omega^\top \omega}{2} + \sum_{i=1}^n g(\xi_i)$$

subject to

$$\begin{aligned} y_i(\omega^\top x_i + b) &\geq 1 - \xi_i & i = 1, \dots, n \\ \xi_i &\geq 0 & i = 1, \dots, n \\ \omega &\in \mathbb{R}^d, b \in \mathbb{R} \end{aligned}$$

where n is the size of the population and $g(\xi_i) = \frac{C}{n}\xi_i$ the **most popular choice for the loss function**.

Ramp Loss Model (Brooks, *OR*, 2011)

- Ramp Loss Function $g(\xi_i) = (\min\{\xi_i, 2\})^+$ yielding the Ψ -learning approach, with $(a)^+ = \max\{a, 0\}$.

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- Ramp Loss Function $g(\xi_i) = (\min\{\xi_i, 2\})^+$ yielding the Ψ -learning approach, with $(a)^+ = \max\{a, 0\}$.

$$\min \frac{\omega^\top \omega}{2} + \frac{C}{n} \left(\sum_{i=1}^n \xi_i + 2 \sum_{i=1}^n z_i \right)$$

s.t.

(RLM)

$$y_i(\omega^\top x_i + b) \geq 1 - \xi_i - M z_i \quad \forall i = 1, \dots, n$$

$$0 \leq \xi_i \leq 2 \quad \forall i = 1, \dots, n$$

$$z \in \{0, 1\}^n$$

$$\omega \in \mathbb{R}^d, b \in \mathbb{R}$$

with $M > 0$ big enough constant.

Expectations (and Troubles)

- In principle, RLM is a **tractable** Mixed-Integer **Convex** Quadratic Problem that nowadays commercial (and even some noncommercial) solvers **should be able to solve**:
 - convex objective function,
 - linear constraints, and
 - binary variables,**not much more difficult** than a standard Mixed-Integer *Linear* Problem.

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 - linear constraints, and
 - binary variables,**not much more difficult** than a standard Mixed-Integer *Linear* Problem.
- However, the **bigM constraints** in the above model **destroy** the chances of the solver to consistently succeed for $n > 50$.
- We consider **23 instances** from Brooks, Type B, $n = 100$, time limit of **3,600 CPU seconds**.

Solving the MIQP by IBM-Cplex

- 23 instances from Brooks, Type B, $n = 100$, time limit of 3,600 CPU seconds.
- IBM-Cplex is able to find the **optimal solution** (%gap of the upper bound, ub) **BUT**
- it fails to improve the **continuous relaxation** by terminating after 1h with a large %gap for the lower bound, lb.

IBM-Cplex				
time (sec.)	nodes	% gap		
		ub	lb	
3,438.49	16,142,440	—	—	
tl	12,841,549	—	23.61	
tl	20,070,294	—	37.82	
tl	20,809,936	—	9.37	
tl	17,105,372	—	26.17	
tl	13,865,833	—	22.67	
tl	14,619,065	—	21.40	
tl	13,347,313	—	14.59	
tl	12,257,994	—	22.22	
tl	13,054,400	—	23.13	
tl	14,805,943	—	12.37	
tl	12,777,936	—	21.97	
tl	14,075,300	—	23.32	
tl	13,994,099	—	12.48	
tl	10,671,225	—	23.08	
tl	12,984,857	—	22.72	
tl	12,564,000	—	14.11	
tl	11,217,844	—	23.45	
tl	12,854,704	—	22.72	
tl	14,018,831	—	12.43	
tl	11,727,308	—	23.55	
tl	15,482,162	—	18.67	
tl	12,258,164	—	14.88	

Reformulating by Complementarity

$$\begin{aligned}
 \min \quad & \frac{\omega^\top \omega}{2} + \frac{C}{n} \left(\sum_{i=1}^n \xi_i + 2 \sum_{i=1}^n (1 - \bar{z}_i) \right) \\
 & (y_i(\omega^\top x_i + b) - 1 + \xi_i) \cdot \bar{z}_i \geq 0 \quad \forall i = 1, \dots, n \\
 & 0 \leq \xi_i \leq 2 \quad \forall i = 1, \dots, n \\
 & \bar{z} \in \{0, 1\}^n \\
 & \omega \in \mathbb{R}^d \\
 & b \in \mathbb{R},
 \end{aligned}$$

where $\bar{z}_i = 1 - z_i$, and

- the resulting model is a **Mixed-Integer Nonconvex Quadratically Constrained Problem** (MIQCP) that IBM-Cplex, like all other commercial solvers initially developed for MILP, cannot solve (yet).

Solving the MIQCP by Couenne

- Despite the nonconvexity of the above MIQCP, there are several options to run the new model as it is and one of them is the open-source solver [Couenne](#) belonging to the Coin-OR arsenal.

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Couenne			
time (sec.)	nodes	% gap	
		ub	lb
163.61	17,131	—	—
1,475.68	181,200	—	—
t1	610,069	14.96	15.38
160.85	25,946	—	—
717.20	131,878	—	—
1,855.16	221,618	—	—
482.19	56,710	—	—
491.26	55,292	—	—
1,819.42	216,831	—	—
807.95	89,894	—	—
536.40	62,291	—	—
1,618.79	196,711	—	—
630.18	83,676	—	—
533.77	65,219	—	—
2,007.62	211,157	—	—
641.05	72,617	—	—
728.93	73,142	—	—
1,784.93	193,286	—	—
752.50	84,538	—	—
412.16	48,847	—	—
2,012.62	223,702	—	—
768.73	104,773	—	—
706.39	70,941	—	—

What does Couenne do?

- Although,
 - Convex MIQP should be much easier than nonconvex MIQCP, and
 - IBM-Cplex is by far more sophisticated than Couenneone can still argue that a comparison in performance between two different solution methods and computer codes is anyway hard to perform.

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- Although,
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 - IBM-Cplex is by far more sophisticated than Couenneone can still argue that a comparison in performance between two different solution methods and computer codes is anyway hard to perform.
- However, the reported results are rather surprising, especially if one digs into the way in which Couenne solves the problem, namely considering three aspects:
 - 1 McCormick Linearization,
 - 2 Branching, and
 - 3 alternative L_1 norm.

McCormick Linearization

- The most crucial observation is that the **complementarity constraints** are internally reformulated by Couenne through the classical **McCormick linearization**

① $\vartheta_i = y_i(\omega^\top x_i + b) - 1 + \xi_i$, with $\vartheta_i^L \leq \vartheta_i \leq \vartheta_i^U$, and

② $u_i = \vartheta_i \bar{z}_i$

for $i = 1, \dots, n$.

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$$\textcircled{1} \quad \vartheta_i = y_i(\omega^\top x_i + b) - 1 + \xi_i, \text{ with } \vartheta_i^L \leq \vartheta_i \leq \vartheta_i^U, \text{ and}$$

$$\textcircled{2} \quad u_i = \vartheta_i \bar{z}_i$$

for $i = 1, \dots, n$. Then, the product corresponding to each new variable u_i is linearized as

$$u_i \geq 0 \tag{5}$$

$$u_i \geq \vartheta_i^L \bar{z}_i \tag{6}$$

$$u_i \geq \vartheta_i + \vartheta_i^U \bar{z}_i - \vartheta_i^U \tag{7}$$

$$u_i \leq \vartheta_i + \vartheta_i^L \bar{z}_i - \vartheta_i^L \tag{8}$$

$$u_i \leq \vartheta_i^U \bar{z}_i \tag{9}$$

again for $i = 1, \dots, n$, where (5) are precisely the complementarity constraints and ϑ_i^L and ϑ_i^U play the role of the bigM.

Branching

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- However, the **default** version of Couenne does **not take advantage** of this possibility and **branches** (first) **on binary** variables \bar{z} 's.
- Thus, again it is **surprising** that such a branching strategy leads to an **improvement over the sophisticated branching framework** of IBM-Cplex.

Alternative L_1 norm

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- In order to answer this question we performed an experiment in which the **quadratic part** of the objective function has been **replaced by its L_1 norm** making the entire bigM model linear. Ultimately, the absolute value of ω is minimized.
- **Computationally**, this has **no effect** and **Couenne continues to consistently outperform MILP solvers** on this very special (modified) class of problems.

Tightening ω 's based on the objective function

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- Among those reductions, we observed that Couenne does a very **simple bound tightening** (at the root node) based on the computation of an **upper bound**, i.e., a feasible solution, of value, say, U

$$\omega_i \in \left[-\sqrt{2U}, \sqrt{2U}\right] \quad \forall i = 1, \dots, d.$$

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- We **did implement** this simple bound tightening in IBM-Cplex and it is already **very effective** by triggering further **propagation on binary** variables (i.e., fixings) but **only if the initial bigM values are tight enough**.
- In other words, when the **bigM values are large** it is very hard to solve the problem without **changing them during search**.

Much more sophisticated propagation

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 - Conversely, branching on the \bar{z}_i
 - either ($\bar{z}_i = 0$) increases the lower bound, thus triggering additional ω tightening,
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 - or ($\bar{z}_i = 1$) tightens the bounds on ϑ_i , thus propagating again on ω .
- Switching off in Couenne any of these components leads to a dramatic degradation in the results.

Initial Bound tightening

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Initial Bound tightening

- Bound reduction at the root node can make use of **enumeration**.
- **Iterative domain reduction**
 - **while** (hope_to_improve) **do**
 - **for each** $i \in [1, d]$ **do**
 - $l_i = \min\{\omega_i : (w, \xi, \bar{z}_i) \in P, Z(w, \xi, \bar{z}_i) \leq U\}$
 - $u_i = \max\{\omega_i : (w, \xi, \bar{z}_i) \in P, Z(w, \xi, \bar{z}_i) \leq U\}$
 - where:
 - P is the set of feasible solutions (including bound constraints),
 - $Z(w, \xi, \bar{z}_i)$ is the cost of solution (w, ξ, \bar{z}_i) , and
 - U is the value of an upper bound.
- The MILPs need **not to** be solved to optimality: l_i and u_i are the **bounds** returned by the MIP **within a node limit**.
- Improve lower and upper bounds for ω_i variables \rightarrow possibly fix some ω_i and/or z_i variables.

Iterated domain reduction

- Iterate domain reduction can be seen as a preprocessing tool.
- The better the initial solution U , the more effective the reduction.
- It can be time consuming, but dramatically improves the results:
 - Use IBM-Cplex for 100k nodes (+ 10 polish nodes) to compute the initial solution U .
 - Use IBM-Cplex for 100k nodes for each lower/upper bound tightening.
 - All instances with $d = 2$ solved to optimality:
average CPU time $\simeq 30$ seconds
average # of nodes: 412k
- Iterating the process allows IBM-Cplex's internal preprocessing tools to propagate the current domain of the variables.

IBM-Cplex work in progress

	optimal value	CPLEX 12.6.0 time	CPLEX w.i.p. time time ratio
1	157,995.00	6799.8	253.8 0.04
2	179,368.00	10000.0	3467.2 0.35
3	220,674.00	10000.0	10000.0 1.00
4	5,225.99	10000.0	314.8 0.03
5	5,957.08	10000.0	10000.0 1.00
6	11,409,600.00	10000.0	7995.7 0.80
7	11,409,100.00	10000.0	521.9 0.05
8	10,737,700.00	10000.0	2300.0 0.23
9	5,705,360.00	10000.0	10000.0 1.00
10	5,704,800.00	10000.0	1015.0 0.10
11	5,369,020.00	10000.0	10000.0 1.00
12	2,853,240.00	10000.0	10000.0 1.00
13	2,852,680.00	10000.0	871.4 0.09
14	2,684,660.00	10000.0	2552.6 0.26
15	1,427,170.00	10000.0	10000.0 1.00
16	1,426,620.00	10000.0	2656.3 0.27
17	1,342,480.00	10000.0	10000.0 1.00
18	714,142.00	10000.0	3841.2 0.38
19	713,583.00	10000.0	942.3 0.09
20	671,396.00	10000.0	8653.7 0.87
21	357,626.00	10000.0	2608.0 0.26
22	357,067.00	10000.0	1094.2 0.11
23	335,852.00	10000.0	10000.0 1.00

Conclusions

- In a broad sense, we have used the SVM with the ramp loss to investigate the possibility of exploiting tools from (nonconvex) MINLP in MILP or (convex) MIQP, essentially, the reverse of the common path.
- More precisely, we have argued that sophisticated (nonconvex) MINLP tools might be very effective to face one of the most structural issues of MILP, which is dealing with the weak continuous relaxations associated with bigM constraints.
- We have shown that the crucial bound reduction can be obtained a priori, in this special case by solving MILPs on the weak bigM formulation.
- More generally, a full integration of such a bound reduction tool for indicator constraints can be obtained by local cuts.

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For example: Couenne branching on continuous

		Couenne default				Couenne continuous			
	optimal value	time (sec.)	nodes	% gap		time (sec.)	nodes	% gap	
				ub	lb			ub	lb
1	157,995.00	163.61	17,131	—	—	323.21	62,873	—	—
2	179,368.00	1,475.68	181,200	—	—	561.95	106,905	—	—
3	220,674.00	tl	610,069	14.96	15.38	490.29	134,758	—	—
4	5,225.99	160.85	25,946	—	—	238.26	65,152	—	—
5	5,957.08	717.20	131,878	—	—	535.70	142,368	—	—
6	11,409,600.00	1,855.16	221,618	—	—	773.62	149,880	—	—
7	11,409,100.00	482.19	56,710	—	—	985.26	195,438	—	—
8	10,737,700.00	491.26	55,292	—	—	535.78	103,806	—	—
9	5,705,360.00	1,819.42	216,831	—	—	726.18	143,234	—	—
10	5,704,800.00	807.95	89,894	—	—	1,031.75	172,794	—	—
11	5,369,020.00	536.40	62,291	—	—	546.78	109,142	—	—
12	2,853,240.00	1,618.79	196,711	—	—	663.69	127,318	—	—
13	2,852,680.00	630.18	83,676	—	—	790.88	160,010	—	—
14	2,684,660.00	533.77	65,219	—	—	510.01	99,802	—	—
15	1,427,170.00	2,007.62	211,157	—	—	717.69	117,670	—	—
16	1,426,620.00	641.05	72,617	—	—	932.44	161,835	—	—
17	1,342,480.00	728.93	73,142	—	—	512.60	83,890	—	—
18	714,142.00	1,784.93	193,286	—	—	720.15	119,761	—	—
19	713,583.00	752.50	84,538	—	—	983.23	168,276	—	—
20	671,396.00	412.16	48,847	—	—	449.68	86,351	—	—
21	357,626.00	2,012.62	223,702	—	—	661.69	110,343	—	—
22	357,067.00	768.73	104,773	—	—	706.15	156,464	—	—
23	335,852.00	706.39	70,941	—	—	493.32	79,719	—	—